

MSC: 00A05

DOI: 10.21538/0134-4889-2018-24-2-40-45

CHARACTERIZATION OF OPTIMAL TRAJECTORIES IN \mathbb{R}^3

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We characterize the set of all trajectories \mathcal{T} of an object t moving in a given corridor Y that are furthest away from a family $\mathbb{S} = \{S\}$ of fixed unfriendly observers. Each observer is equipped with a convex open scanning cone $K(S)$ with vertex S . There are constraints on the multiplicity of covering the corridor Y by the cones K and on the “thickness” of the cones. In addition, pairs S, S' for which $[S, S'] \subset (K(S) \cap K(S'))$ are not allowed. The original problem $\max_{\mathcal{T}} \min\{d(t, S) : t \in \mathcal{T}, S \in \mathbb{S}\}$, where $d(t, S) = \|t - S\|$ for $t \in K(S)$ and $d(t, S) = +\infty$ for $t \notin K(S)$, is reduced to the problem of finding an optimal route in a directed graph whose vertices are closed disjoint subsets (boxes) from $Y \setminus \bigcup_S K(S)$. Neighboring (adjacent) boxes are separated by some cone $K(S)$. An edge is a part $\mathcal{T}(S)$ of a trajectory \mathcal{T} that connects neighboring boxes and optimally intersects the cone $K(S)$. The weight of an edge is the deviation of S from $\mathcal{T}(S)$. A route is optimal if it maximizes the minimum weight.

Keywords: navigation, tracking problem, moving object, observer.

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The paper was received by the Editorial Office on April 17, 2018.

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Cite this article as:

V. I. Berdyshev. Characterization of optimal trajectories in \mathbb{R}^3 , *Trudy Inst. Mat. Mekh. UrO RAN*, 2018, vol. 24, no. 2, pp. 40–45.