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TERMINAL CONTROL OF A NONLINEAR PROCESS UNDER DISTURBANCES

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We consider a nonlinear model of motion of a solid body with deficiency of control parameters. The model contains a disturbance parameter. We propose an open-loop control that takes the system from a given initial state to a given terminal state. Results of numerical calculations are presented for the dynamics of the components of the phase vector and of the controls.

Keywords: terminal control, open-loop control, dynamic game.

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