

**VALIDATION OF A SOLUTION METHOD FOR THE PROBLEM OF  
RECONSTRUCTING THE DYNAMICS OF A MACROECONOMIC SYSTEM**

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For a class of nonlinear control systems, we describe a method for the reconstruction of the dynamics and controls from known inaccurate measurements of state trajectories. The method is based on Pontryagin's maximum principle and Tikhonov's regularization method. A validation of the method is provided.

Keywords: dynamic reconstruction, optimal control, Pontryagin's maximum principle.

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